

4.19

$$(a) [L_z, x] = [x p_y - y p_x, x] = [x p_y, x] - [y p_x, x]$$

$A B, C$

$$L_z = x p_y - y p_x$$

$$[L_z, x] = (x [p_y, x] + [x, x] p_y) - (y [p_x, x] + [y, x] p_x)$$

$$[x p_y, x] \rightarrow [A B, C] = A [B, C] + [A, C] B$$

$$[r_i, p_j] = -[p_i, r_j] = i \hbar \delta_{ij}$$

$$[L_z, x] = x [p_y, x] - y [p_x, x] = i \hbar y$$

$$[L_z, y] = [x p_y, y] - [y p_x, y]$$

$$= (x [p_y, y] + [x, y] p_y) - (y [p_x, y] + [y, y] p_x)$$

$-i \hbar$

$$[L_z, y] = -i \hbar x$$

$$[L_z, z] = [x p_y, z] - [y p_x, z]$$

$$= (x [p_y, z] + [x, z] p_y) - (y [p_x, z] + [y, z] p_x)$$

$$[L_z, z] = 0$$

$$[L_z, p_x] = (x [p_y, p_x] + [x, p_x] p_y) - (y [p_x, p_x] + [y, p_x] p_x)$$

$$[p_i, p_j] = 0 \quad i \hbar \delta_{ij}$$

$$[L_z, p_x] = i \hbar p_y$$

$$[L_z, p_y] = (x[\cancel{p_y, p_y}] + [\cancel{x, p_y}]p_y) - (y[\cancel{p_x, p_y}] + [\cancel{y, p_y}]p_x)$$

$$[L_z, p_y] = -i\hbar p_x$$

$$[L_z, p_z] = (x[\cancel{p_y, p_z}] + [\cancel{x, p_z}]p_y) - (y[\cancel{p_x, p_z}] + [\cancel{y, p_z}]p_x)$$

$$[L_z, p_z] = 0$$

$$(b.) [L_z, L_x] = [L_z, (y p_z - z p_y)]$$

$$= [L_z, y p_z] - [L_z, z p_y]$$

$$[AB, C] = A[B, C] + [A, C]B$$

$$\begin{aligned} \textcircled{1} [L_z, y p_z] &= -[y p_z, L_z] = - (y[\cancel{p_z, L_z}] + [\cancel{y, L_z}]p_z) \\ &= -i\hbar x p_z \end{aligned}$$

$$\begin{aligned} \textcircled{2} -[L_z, z p_y] &= [z p_y, L_z] = (z[\cancel{p_y, L_z}] + [\cancel{z, L_z}]p_y) \\ &= i\hbar z p_x \end{aligned}$$

$$[L_z, L_x] = -i\hbar (x p_z - z p_x) = i\hbar L_y$$

$$\begin{aligned} (c.) [L_z, r^2] &= [L_z, x^2 + y^2 + z^2] = [L_z, x^2] + [L_z, y^2] + [L_z, z^2] \\ &= -\{[x^2, L_z] + [y^2, L_z] + [z^2, L_z]\} \\ &= -\{(x[x, L_z] + [x, L_z]x) + (y[y, L_z] + [y, L_z]y) + (z[z, L_z] + [z, L_z]z)\} \end{aligned}$$

$$[L_z, r^2] = -\left\{ (x[x, L_z] + [x, L_z]x) + (y[y, L_z] + [y, L_z]y) + (z[z, L_z] + [z, L_z]z) \right\}$$

$$[x, L_z] = -[L_z, x] = -i\hbar y$$

$$[y, L_z] = -[L_z, y] = i\hbar x$$

$$[z, L_z] = -[L_z, z] = 0$$

$$[L_z, r^2] = -\left\{ (x(-i\hbar y) + (-i\hbar y)x) + (y(i\hbar x) + (i\hbar x)y) \right\}$$

$$= -i\hbar(-xy - yx + yx + xy) = 0$$

$$[L_z, p^2] = -\left\{ (p_x[p_x, L_z] + [p_x, L_z]p_x) + (p_y[p_y, L_z] + [p_y, L_z]p_y) + (p_z[p_z, L_z] + [p_z, L_z]p_z) \right\}$$

where I've used $p^2 = p_x^2 + p_y^2 + p_z^2$ and just substituted p_i my previous result for $r^2 = x^2 + y^2 + z^2$

$$[L_z, p^2] = -\left\{ (p_x(-i\hbar p_y) + (-i\hbar p_y)p_x) + (p_y(i\hbar p_x) + (i\hbar p_x)p_y) \right\}$$

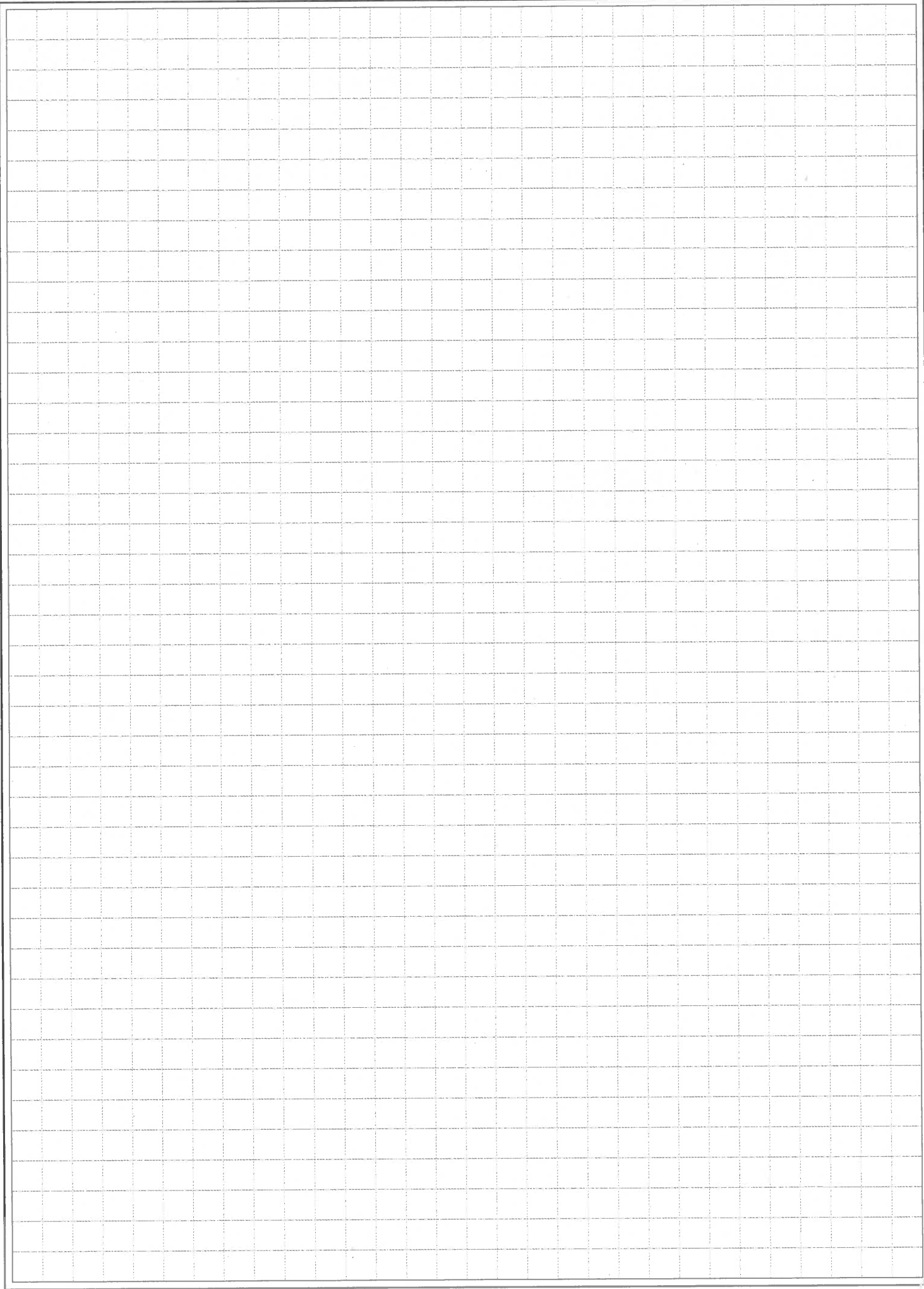
$$= -i\hbar(-p_x p_y + p_y p_x + p_y p_x + p_x p_y)$$

$$[L_z, p^2] = 0$$

$$(d.) \quad H = \frac{p^2}{2m} + V(r) = \frac{p^2}{2m} + V(\sqrt{r^2})$$

In part (c.), we found that L_z commutes w/ p^2 and r^2 , so $[L_z, H] = 0$. However, the same logic in (c.) that held for L_z also holds for L_x and L_y , so $[L_x, H] = [L_y, H]$.

$$\therefore [L_x + L_y + L_z, H] = [L, H] = 0 \quad \text{QED}$$



4.20

(a.)

Let's look @ the L_x component of L

$$\frac{d}{dt} \langle L_x \rangle = \frac{i}{\hbar} \langle [\hat{H}, \hat{L}_x] \rangle + \left\langle \frac{\partial L_x}{\partial t} \right\rangle^0$$

$$[\hat{H}, \hat{L}_x] = \frac{1}{2} [\hat{p}^2, \hat{L}_x] + [V, L_x]$$

From 4.19 (c.), we have $[\hat{p}^2, \hat{L}_x] = 0$, so the 1st term is 0

$$[V, L_x] = [V, y p_z - z p_y] = y [V, p_z] - z [V, p_y]$$

From 3.13 (c.), $[F(x), p] = i\hbar \frac{\partial F}{\partial x}$ for any func. of x

$$\therefore [V, p_z] = i\hbar \frac{\partial V}{\partial z} \quad \text{and} \quad [V, p_y] = i\hbar \frac{\partial V}{\partial y}$$

$$[V, L_x] = y i\hbar \frac{\partial V}{\partial z} - z i\hbar \frac{\partial V}{\partial y} = i\hbar [\vec{r} \times \nabla V]_x$$

$$\frac{d \langle L_x \rangle}{dt} = \frac{i}{\hbar} i\hbar \langle [\vec{r} \times \nabla V]_x \rangle = - \langle [\vec{r} \times \nabla V]_x \rangle$$

Since the same procedure can be used for the y and z components, we have

$$\frac{d \langle \vec{L} \rangle}{dt} = - \langle -\vec{r} \times \nabla V \rangle = \langle \vec{r} \times (-\nabla V) \rangle = \langle \vec{N} \rangle \quad \text{QED}$$

(b.)

For a spherically symmetric potential, $V(\vec{r}) = V(r) \hat{r}$, so $\nabla V = \frac{\partial V}{\partial r} \hat{r}$

But $\vec{r} \times \frac{\partial V}{\partial r} \hat{r} = 0$ since $\hat{r} \times \hat{r} = 0$, so $\frac{d \langle \vec{L} \rangle}{dt} = 0$.

4.21

(5)

$$(a.) L_{\pm} = \pm \hbar e^{\pm i\phi} \left(\frac{\partial}{\partial \theta} \pm i \cot \theta \frac{\partial}{\partial \phi} \right)$$

$$\begin{aligned} L_+ L_- f &= -\hbar^2 \left[e^{+i\phi} \left(\frac{\partial}{\partial \theta} + i \cot \theta \frac{\partial}{\partial \phi} \right) \left(e^{-i\phi} \left[\frac{\partial}{\partial \theta} - i \cot \theta \frac{\partial}{\partial \phi} \right] f \right) \right] \\ &= -\hbar^2 \left\{ e^{i\phi} \left[\frac{\partial}{\partial \theta} + i \cot \theta \frac{\partial}{\partial \phi} \right] \left[e^{-i\phi} \frac{\partial f}{\partial \theta} - i e^{-i\phi} \cot \theta \frac{\partial f}{\partial \phi} \right] \right\} \\ &= -\hbar^2 \left\{ e^{i\phi} \left[e^{-i\phi} \frac{\partial^2 f}{\partial \theta^2} - i e^{-i\phi} \left(\frac{\partial^2 f}{\partial \phi \partial \theta} \cot \theta - \frac{\partial f}{\partial \phi} \csc^2 \theta \right) + i \cot \theta \left(-i e^{-i\phi} \frac{\partial f}{\partial \theta} + e^{-i\phi} \frac{\partial^2 f}{\partial \phi^2} \right) \right. \right. \\ &\quad \left. \left. + \cot^2 \theta \left(-i e^{-i\phi} \frac{\partial f}{\partial \phi} + e^{-i\phi} \frac{\partial^2 f}{\partial \phi^2} \right) \right] \right\} \\ &= -\hbar^2 \left\{ \frac{\partial^2 f}{\partial \theta^2} - i \cot \theta \frac{\partial^2 f}{\partial \phi \partial \theta} + i \cot \theta \frac{\partial^2 f}{\partial \phi \partial \theta} + i \left(\csc^2 \theta \frac{\partial f}{\partial \phi} - \cot^2 \theta \frac{\partial f}{\partial \phi} \right) + \right. \\ &\quad \left. \cot \theta \frac{\partial f}{\partial \theta} + \cot^2 \theta \frac{\partial^2 f}{\partial \phi^2} \right\} \end{aligned}$$

$$\frac{1}{\csc^2 \theta} - \frac{\cot^2 \theta}{\cot^2 \theta} = 1$$

$$= -\hbar^2 \left\{ \frac{\partial^2}{\partial \theta^2} + i \frac{\partial}{\partial \phi} + \cot \theta \frac{\partial}{\partial \theta} + \cot^2 \theta \frac{\partial^2}{\partial \phi^2} \right\} f \quad \left. \begin{array}{l} \text{dropping the} \\ \text{test function} \end{array} \right\}$$

$$L_+ L_- = -\hbar^2 \left\{ \frac{\partial^2}{\partial \theta^2} + \cot \theta \frac{\partial}{\partial \theta} + \cot^2 \theta \frac{\partial^2}{\partial \phi^2} + i \frac{\partial}{\partial \phi} \right\} \quad \text{QED}$$

$$(b.) L_z = -i\hbar \frac{\partial}{\partial \phi}$$

$$L^2 = L_+ L_- + L_z^2 = \hbar L_z$$

$$\begin{aligned} L^2 &= L_+ L_- + L_z^2 = \hbar L_z = -\hbar^2 \left\{ \frac{\partial^2}{\partial \theta^2} + \cot \theta \frac{\partial}{\partial \theta} + \cot^2 \theta \frac{\partial^2}{\partial \phi^2} + i \frac{\partial}{\partial \phi} \right\} + \\ &\quad \left(-\hbar^2 \right) \frac{\partial^2}{\partial \phi^2} + i \hbar^2 \frac{\partial}{\partial \phi} \\ &= -\hbar^2 \left\{ \frac{\partial^2}{\partial \theta^2} + \cot \theta \frac{\partial}{\partial \theta} + \cot^2 \theta \frac{\partial^2}{\partial \phi^2} + i \frac{\partial}{\partial \phi} + \frac{\partial^2}{\partial \phi^2} - i \frac{\partial}{\partial \phi} \right\} \end{aligned}$$

$$L^2 = -\hbar^2 \left\{ \frac{\partial^2}{\partial \theta^2} + \frac{\cos \theta}{\sin \theta} \frac{\partial}{\partial \theta} + \left(\frac{\cos^2 \theta + \sin^2 \theta}{\sin^2 \theta} \right) \frac{\partial^2}{\partial \phi^2} \right\}$$

$$= -\hbar^2 \left\{ \frac{\partial^2}{\partial \theta^2} + \frac{\cos \theta}{\sin \theta} \frac{\partial}{\partial \theta} + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \phi^2} \right\}$$

this term can be written as: $\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (\sin \theta \frac{\partial}{\partial \theta}) = \frac{\cos \theta}{\sin \theta} \frac{\partial}{\partial \theta} + \frac{\partial^2}{\partial \theta^2}$

$$\therefore L^2 = -\hbar^2 \left[\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (\sin \theta \frac{\partial}{\partial \theta}) + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \phi^2} \right] \quad QED$$

4.22

(a) $L_+ Y_l^l = 0$ since this is the highest rung of the ladder ($m = |l|$).

(b) $L_+ Y_l^l = 0$, where $L_+ = \hbar e^{+i\phi} \left(\frac{\partial}{\partial \theta} + i \cot \theta \frac{\partial}{\partial \phi} \right)$

$L_z Y_l^l = \hbar l Y_l^l$ (same as $L_z Y_l^m = m \hbar Y_l^m$, just w/ $l = m$)

But $L_z = -i \hbar \frac{\partial}{\partial \phi}$ so: $-i \hbar \frac{\partial Y_l^l}{\partial \phi} = \hbar l Y_l^l$ acts like a constant in this DE

$$\frac{\partial Y_l^l}{\partial \phi} = i l Y_l^l \rightarrow Y_l^l = g(\theta) e^{i l \phi}$$

$$L_+ Y_l^l = 0 \Rightarrow \hbar e^{i\phi} \left(\frac{\partial}{\partial \theta} + i \cot \theta \frac{\partial}{\partial \phi} \right) g(\theta) e^{i l \phi} = 0$$

$$\frac{dg}{d\theta} e^{i l \phi} - l \cot \theta g(\theta) e^{i l \phi} = 0$$

$$\frac{dg}{d\theta} = l \cot \theta g$$

$$u = \sin \theta$$

$$du = \cos \theta d\theta$$

$$\int \frac{dg}{g} = \int l \cot \theta d\theta = \int \frac{\cos \theta d\theta}{\sin \theta} = \int \frac{du}{u}$$

$$\ln g = \ln u + C = \ln(\sin \theta) + C$$

$$\ln g = \ln(\sin^l \theta) + C$$

$$g(\theta) = A \sin^l \theta$$

$$\therefore Y_l^l = g(\theta) e^{il\phi} = \boxed{A (\sin \theta e^{i\phi})^l}$$

$$\begin{aligned} \text{(c.) } 1 &= \int_0^{2\pi} \int_0^\pi |Y_l^l|^2 \sin \theta d\theta d\phi = \int_0^{2\pi} \int_0^\pi |A|^2 \sin^{2l} \theta \sin \theta e^{-i\phi} e^{i\phi} d\phi \\ &= 2\pi |A|^2 \int_0^\pi \sin^{2l} \theta \sin \theta d\theta = 2\pi |A|^2 \int_0^\pi \sin^{(2l+1)} \theta d\theta \\ &= 2\pi |A|^2 2 \left[\frac{2 \cdot 4 \cdot 6 \cdot 8 \cdots 2l}{1 \cdot 3 \cdot 5 \cdot 7 \cdots (2l+1)} \right] \end{aligned}$$

In order to make the numerator a squared quantity, we can multiply the top and bottom by $2 \cdot 4 \cdot 6 \cdot 8 \cdots 2l$ to get:

$$1 = 4\pi |A|^2 \frac{(2 \cdot 4 \cdot 6 \cdots 2l)^2}{(2l+1)!}$$

$$\begin{aligned} 2 \cdot 4 \cdot 6 \cdot 8 \cdots 2l &= (2 \cdot 1) \cdot (2 \cdot 2) \cdot (2 \cdot 3) \cdot (2 \cdot 4) \cdots 2 \cdot l \\ &= 2^l l! \end{aligned}$$

$$1 = 4\pi A^2 \frac{(2^l l!)^2}{(2l+1)!} \rightarrow A = \frac{1}{2^l l!} \sqrt{\frac{(2l+1)!}{4\pi}} = \frac{1}{2^{l+1/2} l!} \sqrt{\frac{(2l+1)!}{\pi}}$$

4

$$\vec{J} \equiv \frac{i\hbar}{2\mu} (\psi \nabla \psi^* - \psi^* \nabla \psi)$$

$$(a) \quad \psi_{211} = \frac{1}{\sqrt{24}} a_0^{-3/2} \frac{r}{a_0} \exp(-r/2a_0) \left(-\left[\frac{3}{8\pi}\right]^{1/2} \sin\theta e^{i\phi} \right)$$

$$= -\frac{1}{8\sqrt{\pi}} \sqrt{\frac{1}{a_0^3}} r \sin\theta e^{-r/2a_0} e^{i\phi}$$

$$\nabla \psi = \frac{-1}{8a_0^2 \sqrt{\pi} a_0} \left[\sin\theta e^{i\phi} \left(1 - \frac{r}{2a_0}\right) e^{-r/2a_0} \hat{r} + \frac{r}{r} e^{-r/2a_0} e^{i\phi} \cos\theta \hat{\theta} + \frac{i}{r \sin\theta} r e^{-r/2a_0} \sin\theta e^{i\phi} \hat{\phi} \right]$$

$$\nabla \psi = \frac{-1}{8a_0^2 \sqrt{\pi} a_0} \left[\sin\theta \left(1 - \frac{r}{2a_0}\right) \hat{r} + \cos\theta \hat{\theta} + i \hat{\phi} \right] e^{-r/2a_0} e^{i\phi}$$

Similarly:

$$\nabla \psi^* = \frac{-1}{8a_0^2 \sqrt{\pi} a_0} \left[\sin\theta \left(1 - \frac{r}{2a_0}\right) \hat{r} + \cos\theta \hat{\theta} - i \hat{\phi} \right] e^{-r/2a_0} e^{-i\phi}$$

$$\textcircled{1} \quad \psi \nabla \psi^* = \frac{r \sin\theta}{64 a_0^3 \pi} \left[\sin\theta \left(1 - \frac{r}{2a_0}\right) \hat{r} + \cos\theta \hat{\theta} - i \hat{\phi} \right] e^{-r/a_0}$$

$$\textcircled{2} \quad \psi^* \nabla \psi = \frac{r \sin\theta}{64 a_0^3 \pi} \left[\sin\theta \left(1 - \frac{r}{2a_0}\right) \hat{r} + \cos\theta \hat{\theta} + i \hat{\phi} \right] e^{-r/a_0}$$

Subtracting gives:

$$\textcircled{1} - \textcircled{2} = \frac{-2r \sin\theta}{64 a_0^3 \pi} e^{-r/a_0} \hat{\phi}$$

$$\vec{J} = \frac{i\hbar}{2\mu} \left(\frac{-2r \sin\theta}{64 \pi a_0^3} e^{-r/a_0} \hat{\phi} \right) = \frac{\hbar}{64 \pi \mu a_0^3} r \sin\theta e^{-r/a_0} \hat{\phi}$$

(b.)

$$L = \mu \int \vec{r} \times \vec{J} d^3r$$

$$\vec{r} \times \vec{J} = \frac{\hbar}{64 \pi \mu a_0^3} r^2 \sin\theta e^{-r/a_0} (\hat{r} \times \hat{\phi}) =$$

1 3 = -2

Since we want L_z , we must find the z^{th} component of $\vec{r} \times \vec{J}$. $\vec{r} \times \vec{J}$ is in the $-\hat{\theta}$ direction, so the z^{th} component

of $\vec{r} \times \vec{j}$ is just $-\hat{z} \cdot \hat{\theta}$, which is:

$$-(\hat{z} \cdot \hat{\theta}) = -(\cos\theta \hat{r} - \sin\theta \hat{\theta}) \cdot \hat{\theta} = -(-\sin\theta) = \sin\theta$$

$$L_z = \mu \int \frac{\hbar}{64\pi^2 a_0^5} r^2 \sin^2\theta e^{-r/a_0} dV = \frac{2\pi\hbar}{64\pi a_0^5} \int_0^\infty r^4 e^{-r/a_0} dr \int_0^\pi \sin\theta (1 - \cos^2\theta) d\theta$$

① $\int_0^\pi \sin\theta d\theta = -\cos\theta \Big|_0^\pi = 2$

$-\int_0^\pi \sin\theta \cos^2\theta d\theta$ $u = \cos\theta$
 $du = -\sin\theta d\theta$

$$-\int_{-1}^1 u^2 du = -\frac{u^3}{3} \Big|_{-1}^1 = -\left[\frac{1}{3} - \left(-\frac{1}{3}\right)\right] = -\frac{2}{3}$$

$$2 - \frac{2}{3} = \frac{4}{3}$$

② $\int_0^\infty r^4 e^{-r/a_0} dr =$

r^4	\oplus	e^{-r/a_0}
$4r^3$	\ominus	$-a_0 e^{-r/a_0}$
$12r^2$	\oplus	$2 a_0^2 e^{-r/a_0}$
$24r$	\ominus	$-3 a_0^3 e^{-r/a_0}$
24	\oplus	$4 a_0^4 e^{-r/a_0}$
0	\ominus	$-5 a_0^5 e^{-r/a_0}$

Since all e^{-r/a_0} terms go to 0 faster than r^n goes to ∞ where $r \rightarrow \infty$. Similarly, all r^n ($n \geq 1$) terms go to 0 when $r \rightarrow 0$.

$$\therefore \int_0^\infty r^4 e^{-r/a_0} dr = 24 a_0^5$$

$$L_z = \frac{\hbar}{32a_0^5} \underbrace{24a_0^5}_{(2)} \underbrace{\frac{4}{3}}_{(1)} = \hbar$$

This is exactly the result we expect, since

$$\hat{L}_z |l m\rangle = m\hbar |l m\rangle$$

$$\hat{L}_z |1 1\rangle = \hbar |1 1\rangle \text{ for } \psi_{211}$$

