

$$\psi_{210} = \frac{1}{4a^{5/2}} \sqrt{\frac{1}{2\pi}} r e^{-r/2a} \cos\theta e^{-i\omega_1 t}$$

$$\psi_{211} = \frac{-1}{8a^{5/2}} \sqrt{\frac{1}{\pi}} r e^{-r/2a} \sin\theta e^{-i(\omega_2 t - \phi)}$$

$$\psi = \sqrt{\frac{1}{2}} (\psi_{210} + \psi_{211})$$

$$\psi = \underbrace{\left[\frac{1}{8a^{5/2}} \sqrt{\frac{1}{\pi}} r e^{-r/2a} \right]}_{A R(r)} \left[\cos\theta e^{-i\omega_1 t} - \sqrt{\frac{1}{2}} \sin\theta e^{-i(\omega_2 t - \phi)} \right]$$

$$\psi^* = A R(r) \left[\cos\theta e^{i\omega_1 t} - \sqrt{\frac{1}{2}} \sin\theta e^{-i(\omega_2 t - \phi)} \right]$$

$$\bar{J}_e(\vec{r}, t) = -\frac{ieh}{2m} (\psi \nabla \psi^* - \psi^* \nabla \psi)$$

$$\bar{u}_m(t) = \int_V \vec{r} \times \bar{J}_e(\vec{r}, t) dV$$

$$\bar{\nabla} = \frac{\partial}{\partial r} \hat{r} + \frac{1}{r} \frac{\partial}{\partial \theta} \hat{\theta} + \frac{1}{r \sin\theta} \frac{\partial}{\partial \phi} \hat{\phi}$$

Let's first calculate our operator $\vec{r} \times \bar{\nabla}$

$$\vec{r} \times \bar{\nabla} = r \hat{r} \times \bar{\nabla} = \frac{\partial}{\partial \theta} \hat{\phi} - \frac{1}{\sin\theta} \frac{\partial}{\partial \phi} \hat{\theta}, \text{ where } \hat{r} \times \hat{r} = 0$$

$$\vec{r} \times \bar{\nabla} = \frac{-1}{\sin\theta} \frac{\partial}{\partial \phi} \hat{\theta} + \frac{\partial}{\partial \theta} \hat{\phi}$$

$$\hat{r} \times \hat{\theta} = \hat{\phi}$$

$$\hat{r} \times \hat{\phi} = -\hat{\theta}$$

This says that $R(r)$ can be treated as a constant until we calculate $\int_V \vec{r} \times \bar{J}_e(\vec{r}, t) dV$

Calculation of $\vec{r} \times \vec{J}_e(\vec{r}, t)$:

First, let's break up the problem a little:

$$\vec{r} \times \vec{J}_e(\vec{r}, t) = \frac{-ie\hbar}{2m} [\psi(\vec{r} \times \nabla \psi^*) - \psi^*(\vec{r} \times \nabla \psi)]$$

We can do this b/c ψ and ψ^* both act like constants in this situation

$$\begin{aligned} \vec{r} \times \nabla \psi^* &= AR(r) \left[\frac{-1}{\sin\theta} \frac{\partial}{\partial\phi} (Y_1^0 e^{i\omega_1 t} + Y_1^1 e^{i\omega_2 t}) \hat{\theta} + \frac{\partial}{\partial\theta} (Y_1^0 e^{i\omega_1 t} + Y_1^1 e^{i\omega_2 t}) \hat{\phi} \right] \\ &= AR(r) \left[-i\sqrt{\frac{1}{2}} \frac{\sin\theta}{\sin\theta} e^{i(\omega_2 t - \phi)} \hat{\theta} + \left(-\sin\theta e^{i\omega_1 t} - \sqrt{\frac{1}{2}} \cos\theta e^{i(\omega_2 t - \phi)} \right) \hat{\phi} \right] \end{aligned}$$

$$\vec{r} \times \nabla \psi = AR(r) \left[i\sqrt{\frac{1}{2}} \frac{\sin\theta}{\sin\theta} e^{-i(\omega_2 t - \phi)} \hat{\theta} + \left(-\sin\theta e^{-i\omega_1 t} - \sqrt{\frac{1}{2}} \cos\theta e^{-i(\omega_2 t - \phi)} \right) \hat{\phi} \right]$$

$$\begin{aligned} \textcircled{1} \psi(\vec{r} \times \nabla \psi^*) &= A^2 R^2(r) \left[\cos\theta e^{-i\omega_1 t} - \sqrt{\frac{1}{2}} \sin\theta e^{-i(\omega_2 t - \phi)} \right] \left[-i\sqrt{\frac{1}{2}} e^{i(\omega_2 t - \phi)} \hat{\theta} \right. \\ &+ \left. \left(-\sin\theta e^{i\omega_1 t} - \sqrt{\frac{1}{2}} \cos\theta e^{i(\omega_2 t - \phi)} \right) \hat{\phi} \right] \\ &= A^2 R^2(r) \left\{ \left[\frac{-i}{\sqrt{2}} \cos\theta e^{i(\omega_2 t - \phi)} + \frac{i}{2} \sin\theta \right] \hat{\theta} + \left[-\cos\theta \sin\theta - \frac{\cos^2\theta}{\sqrt{2}} e^{i(\omega_2 t - \phi)} \right. \right. \\ &+ \left. \left. \frac{\sin^2\theta}{\sqrt{2}} e^{-i(\omega_2 t - \phi)} + \frac{\sin\theta \cos\theta}{2} \right] \hat{\phi} \right\} \end{aligned}$$

$$\begin{aligned} \textcircled{2} \psi^*(\vec{r} \times \nabla \psi) &= A^2 R^2(r) \left[\cos\theta e^{i\omega_1 t} - \sqrt{\frac{1}{2}} \sin\theta e^{i(\omega_2 t - \phi)} \right] \left[\frac{i}{\sqrt{2}} e^{-i(\omega_2 t - \phi)} \hat{\theta} + \left(-\sin\theta e^{-i\omega_1 t} - \right. \right. \\ &\left. \left. \sqrt{\frac{1}{2}} \cos\theta e^{-i(\omega_2 t - \phi)} \right) \hat{\phi} \right] \\ &= A^2 R^2(r) \left\{ \left[\frac{i \cos\theta}{\sqrt{2}} e^{-i(\omega_2 t - \phi)} - \frac{i}{2} \sin\theta \right] \hat{\theta} + \left[-\cos\theta \sin\theta - \frac{\cos^2\theta}{\sqrt{2}} e^{-i(\omega_2 t - \phi)} \right. \right. \\ &+ \left. \left. \frac{\sin^2\theta}{\sqrt{2}} e^{i(\omega_2 t - \phi)} + \frac{\cos\theta \sin\theta}{2} \right] \hat{\phi} \right\} \end{aligned}$$

$$\vec{r} \times \vec{J}_e(\vec{r}, t) = \frac{-i e \hbar}{2m} A^2 R^2(r) \left\{ \left[\frac{-i \cos \theta}{\sqrt{2}} \left(e^{i(\omega_{21} t - \phi)} + e^{-i(\omega_{21} t - \phi)} \right) + i \sin \theta \right] \hat{\theta} \right.$$

$$\left. \left[-\cos \theta \sin \theta + \cos \theta \sin \theta - \frac{\cos^2 \theta}{\sqrt{2}} \left(e^{i(\omega_{21} t - \phi)} - e^{-i(\omega_{21} t - \phi)} \right) + \frac{\sin^2 \theta}{\sqrt{2}} \left(e^{-i(\omega_{21} t - \phi)} - e^{i(\omega_{21} t - \phi)} \right) \right. \right.$$

$$\left. \left. + \frac{\sin \theta \cos \theta}{2} - \frac{\sin \theta \cos \theta}{2} \right] \hat{\phi} \right\}$$

$$\vec{r} \times \vec{J}_e(\vec{r}, t) = \frac{e \hbar}{2m} A^2 R^2(r) \left\{ \left[-\sqrt{2} \cos \theta \cos(\omega_{21} t - \phi) + \sin \theta \right] \hat{\theta} + \left[-\sqrt{2} \sin(\omega_{21} t - \phi) \right] \hat{\phi} \right\}$$

$$\vec{u}_m(t) = \int \vec{r} \times \vec{J}_e(\vec{r}, t) dV = \frac{e \hbar}{2m} A^2 \int_{r=0}^{\infty} r^2 R^2(r) \int_{\theta=0}^{\pi} \int_{\phi=0}^{2\pi} \left\{ \left[-\sqrt{2} \cos \theta \cos(\omega_{21} t - \phi) + \sin \theta \right] \hat{\theta} + \left[-\sqrt{2} \sin(\omega_{21} t - \phi) \right] \hat{\phi} \right\} r^2 dr d\theta d\phi$$

① $\int_0^{\infty} r^2 R^2(r) dr = \int_0^{\infty} r^4 e^{-r/a} dr \rightarrow$

r^4	\ominus	$e^{-r/a}$
$4r^3$	\ominus	$-a e^{-r/a}$
$12r^2$	\ominus	$a^2 e^{-r/a}$
$24r$	\ominus	$-a^3 e^{-r/a}$
24	\ominus	$a^4 e^{-r/a}$
0	\oplus	$-a^5 e^{-r/a}$

Since we are evaluating our terms from $r=0$ to ∞ , any (anti-derivative) term w/ r in it is $0 @ r=0$. Similarly, $e^{-r/a} \rightarrow 0 @ r=\infty$. Therefore, the only term that survives is $-24a^5 e^{-r/a}$ evaluated @ $\infty(0)$ and $0(24a^5)$.

$$\therefore \int_0^{\infty} r^4 e^{-r/a} dr = 24a^5 = \textcircled{1}$$

$$\int_{\theta=0}^{\pi} \int_{\varphi=0}^{2\pi} [-\sqrt{2} \cos\theta \cos(\omega_{z1}t - \varphi) + \sin\theta] \hat{\theta} \sin\theta d\theta d\varphi$$

$$\hat{\theta} = \cos\theta \cos\varphi \hat{x} + \cos\theta \sin\varphi \hat{y} - \sin\theta \hat{z}$$

$$\int_{\theta=0}^{\pi} \int_{\varphi=0}^{2\pi} [-\sqrt{2} \cos\theta \sin\theta \cos(\omega_{z1}t - \varphi) + \sin^2\theta] [\cos\theta \cos\varphi \hat{x} + \cos\theta \sin\varphi \hat{y} - \sin\theta \hat{z}] d\theta d\varphi$$

$$\int_{\theta=0}^{\pi} \int_{\varphi=0}^{2\pi} [-\sqrt{2} \cos^2\theta \sin\theta \cos\varphi \cos(\omega_{z1}t - \varphi) + \sin^2\theta \cos\theta \cos\varphi] \hat{x} +$$

$$[-\sqrt{2} \cos^2\theta \sin\theta \sin\varphi \cos(\omega_{z1}t - \varphi) + \sin^2\theta \cos\theta \sin\varphi] \hat{y} +$$

$$[\sqrt{2} \cos\theta \sin^2\theta \cos(\omega_{z1}t - \varphi) - \sin^3\theta] \hat{z} d\theta d\varphi$$

(φ integral)

(φ integral)

Let's find the θ integrals first:

$$\int_0^{\pi} \cos^2\theta \sin\theta d\theta = \int_{-1}^1 x^2 dx, \text{ where } x = \cos\theta \text{ and } dx = -\sin\theta d\theta$$

$$= \frac{x^3}{3} \Big|_{-1}^1 = \frac{2}{3}$$

$$\int_0^{\pi} \sin^3\theta d\theta = \int_0^{\pi} \sin\theta d\theta - \int_0^{\pi} \cos^2\theta \sin\theta d\theta = -\cos\theta \Big|_0^{\pi} - \frac{2}{3}$$

$$= 2 - \frac{2}{3} = \frac{4}{3}$$

Now our integral looks like:

$$-\frac{2\sqrt{2}\hat{x}}{3} \int_{\varphi=0}^{2\pi} \cos\varphi \cos(\omega_{21}t - \varphi) d\varphi + \frac{-2\sqrt{2}}{3} \hat{y} \int_{\varphi=0}^{2\pi} \sin\varphi \cos(\omega_{21}t - \varphi) d\varphi - \frac{4\hat{z}}{3} \int_{\varphi=0}^{2\pi} d\varphi$$

$\cos(\omega_{21}t - \varphi)$ can be broken down as: $\cos\omega_{21}t \cos\varphi + \sin\omega_{21}t \sin\varphi$

$$-\frac{2\sqrt{2}}{3} \hat{x} \int_0^{2\pi} (\cos^2\varphi \cos\omega_{21}t + \cancel{\cos\varphi \sin\varphi \sin\omega_{21}t}) d\varphi - \frac{2\sqrt{2}}{3} \hat{y} \int_0^{2\pi} (\cancel{\sin\varphi \cos\varphi \cos\omega_{21}t} + \sin^2\varphi \sin\omega_{21}t) d\varphi - \frac{8\pi}{3} \hat{z}$$

$$+ \sin^2\varphi \sin\omega_{21}t) d\varphi - \frac{8\pi}{3} \hat{z}$$

$$\int_0^{2\pi} \cos^2\theta d\theta = \int_0^{2\pi} \sin^2\theta d\theta = \pi$$

$$\therefore \textcircled{2} \text{ is equal to } \left| -\frac{2\pi\sqrt{2}}{3} \cos\omega_{21}t \hat{x} - \frac{2\pi\sqrt{2}}{3} \sin\omega_{21}t \hat{y} - \frac{8\pi}{3} \hat{z} \right|$$

③

$$\int_{\theta=0}^{\pi} \int_{\varphi=0}^{2\pi} [-\sqrt{2} \sin\theta \sin(\omega_{21}t - \varphi)] \hat{\varphi} d\theta d\varphi$$

$$\hat{\varphi} = -\sin\varphi \hat{x} + \cos\varphi \hat{y}$$

$$\int_{\theta=0}^{\pi} \sin\theta d\theta = -\cos\theta \Big|_0^{\pi} = 2$$

$$-2\sqrt{2} \int_{\varphi=0}^{2\pi} \sin(\omega_{21}t - \varphi) [-\sin\varphi \hat{x} + \cos\varphi \hat{y}] d\varphi$$

$$\sin(\omega_{21}t - \varphi) = \sin\omega_{21}t \cos\varphi - \cos\omega_{21}t \sin\varphi$$

$$-2\sqrt{2} \int_{\varphi=0}^{2\pi} [-\cancel{\sin\omega_{21}t \sin\varphi \cos\varphi} \hat{x} + \cos\omega_{21}t \sin^2\varphi \hat{x} + \sin\omega_{21}t \cos^2\varphi \hat{y} - \cancel{\cos\omega_{21}t \cos\varphi \sin\varphi} \hat{y}] d\varphi$$

$$\textcircled{3} = -2\pi\sqrt{2} [\cos\omega_{21}t \hat{x} + \sin\omega_{21}t \hat{y}]$$

Putting this altogether:

$$\bar{u}_m(t) = \frac{e\hbar}{2m} \frac{1}{64\pi a^5} \frac{24a^5}{8A^2} \left\{ \frac{-2\pi\sqrt{2}}{3} \cos\omega_{21}t \hat{x} - \frac{2\pi\sqrt{2}}{3} \sin\omega_{21}t \hat{y} \right.$$

$$\left. - \frac{8\pi}{3} \hat{z} - 2\pi\sqrt{2} \cos\omega_{21}t \hat{x} - 2\pi\sqrt{2} \sin\omega_{21}t \hat{y} \right\}$$

$$= \frac{-3e\hbar}{16m} \left\{ \left(\frac{2\sqrt{2}}{3} + 2\sqrt{2} \right) \cos\omega_{21}t \hat{x} + \left(\frac{2\sqrt{2}}{3} + 2\sqrt{2} \right) \sin\omega_{21}t \hat{y} + \frac{8}{3} \hat{z} \right\}$$

$$\bar{u}_m(t) = \frac{-e\hbar}{2m} \left\{ \sqrt{2} \cos\omega_{21}t \hat{x} + \sqrt{2} \sin\omega_{21}t \hat{y} + \hat{z} \right\}$$